# Estimating Gaussian Mixtures Using Sparse Polynomial Moment Systems

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Online Machine Learning Seminar

**UT** Austin

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### Theorem (Chapter 3 [GBC16])

A Gaussian mixture model is a universal approximator of densities, in the sense that any smooth density can be approximated with any specific nonzero amount of error by a Gaussian mixture model with enough components.

### Gaussian Mixture Models

• A random variable  $X = \mathcal{N}(\mu, \sigma^2)$  is a *Gaussian* random variable if it has density

$$f(xj\mu,\sigma^2) = P \frac{1}{2\pi\sigma^2} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right).$$

 X is distributed as a mixture of k Gaussians if it is the convex combination of k Gaussian densities

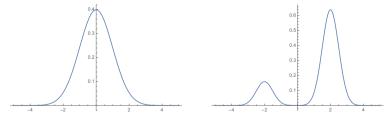


Figure:  $\mathcal{N}(0,1)$  density (left) and  $0.2\mathcal{N}(2,0.5) + 0.8\mathcal{N}(2,0.5)$  density (right).

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$$\operatorname{argmax}_{\mu,\sigma^2,\lambda} \quad \prod_{j=1}^{N} \sum_{i=1}^{k} \lambda_i \frac{1}{\sqrt{2\pi\sigma_i^2}} \exp\left(-\frac{(y_j - \mu_i)^2}{2\sigma_i^2}\right)$$

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  - Local optima can be arbitrarily bad and random initialization will converge to these bad points with probability 1  $e^{\Omega(k)}$  [JZB+16]

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  - Need to access all samples at each iteration

Method of Moments

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  - IF you can solve the moment equations, then can recover exact parameters

• For *i* 0, the *i* th moment of a random variable *X* with density *f* is

$$m_i = \mathbb{E}[X^i] = \int_{\mathbb{R}} x^i f(x) dx$$

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- For parameterized distributions, moments are functions of parameters
- Ex. The first few moments of a  $\mathcal{N}(\mu, \sigma^2)$  random variable are:

$$m_1 = \mu,$$
  $m_2 = \mu^2 + \sigma^2,$   $m_3 = \mu^3 + 3\mu\sigma^2$ 

• Consider a statistical model with p unknown parameters,  $\theta = (\theta_1, \dots, \theta_p)$  and the moments up to order M as functions of  $\theta$ 

$$m_1 = g_1(\theta), \ldots, m_M = g_M(\theta)$$

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  - Compute sample moments

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- Method of Moments:
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$$\overline{m}_i = \frac{1}{N} \sum_{j=1}^N y_j^i$$

**2** Solve  $g_i(\theta) = \overline{m}_i$  for i = 1, ..., M to recover parameters

#### Gaussian Mixture Models

• The moments of the Gaussian distributions are  $M_0(\mu, \sigma^2) = 1$ ,  $M_1(\mu, \sigma^2) = \mu$ ,

$$M_{\ell}(\mu, \sigma^2) = \mu M_{\ell-1} + (\ell - 1)\sigma^2 M_{\ell-2}, \qquad \ell - 2$$

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• The moments of mixtures of k Gaussians are

$$m_{\ell} = \sum_{i=1}^{k} \lambda_i M_{\ell}(\mu_i, \sigma_i^2), \qquad \ell = 0$$

# Method of Moments k = 1

• When k=1 this is just density estimation for  $\mathcal{N}(\mu_1, \sigma_1^2)$ 

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• There is a unique solution given by

$$\lambda_1 = 1, \qquad \mu_1 = \overline{m}_1, \qquad \sigma_1^2 = \overline{m}_2 \quad \overline{m}_1^2$$

k = 2

• When k = 2, the first 6 moment equations are

$$\begin{split} 1 &= \lambda_1 + \lambda_2 \\ \overline{m}_1 &= \lambda_1 \mu_1 + \lambda_2 \mu_2 \\ \overline{m}_2 &= \lambda_1 (\mu_1^2 + \sigma_1^2) + \lambda_2 (\mu_2^2 + \sigma_2^2) \\ \overline{m}_3 &= \lambda_1 (\mu_1^3 + 3\mu_1 \sigma_1^2) + \lambda_2 (\mu_2^3 + 3\mu_2 \sigma_2^2) \\ \overline{m}_4 &= \lambda_1 (\mu_1^4 + 6\mu_1^2 \sigma_1^2 + 3\sigma_1^4) + \lambda_2 (\mu_2^4 + 6\mu_2^2 \sigma_2^2 + 3\sigma_2^4) \\ \overline{m}_5 &= \lambda_1 (\mu_1^5 + 10\mu_1^3 \sigma_1^2 + 15\mu_1 \sigma_1^4) + \lambda_2 (\mu_2^5 + 10\mu_2^3 \sigma_2^2 + 15\mu_2 \sigma_2^4) \end{split}$$

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• **Obervation:** If  $(\lambda_1, \mu_1, \sigma_1^2, \lambda_2, \mu_2, \sigma_2^2)$  is a solution, so is  $(\lambda_2, \mu_2, \sigma_2^2, \lambda_1, \mu_1, \sigma_1^2)$ 

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  - This symmetry is called label swapping
  - For a k mixture model, solutions will come in groups of k!

#### History Detour

 The study of mixtures of Gaussians dates back to Karl Pearson in 1894 studying measurements of Naples crab populations [Pea94]

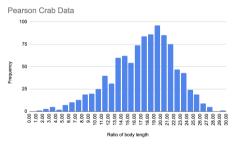


Figure: Pearson's crab data

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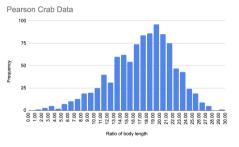


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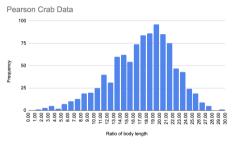


Figure: Pearson's crab data

- ullet Pearson reduced this to finding roots of degree 9 polynomial in the variable  $x=\mu_1\mu_2$
- **Framework:** Solve square polynomial system to get finitely many potential densities then select one closest to the next sample moments

### Identifiability

Different notions of identifiability based on fiber of map:

$$\Phi_M : \Delta_{k-1} \quad \mathbb{R}^k \quad \mathbb{R}^k_{>0} / \mathbb{R}^M$$

$$(\lambda, \mu, \sigma^2) \not V \quad (m_0, \dots, m_M)$$

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- **1** Algebraic: For what M is  $j\Phi_M^{-1}(m)j < 1$  for almost all  $m \ge \text{Im}(\Phi_M)$ ?
  - 3*k* 1 [ARS18]

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- ② Statistical: For what M does  $j\Phi_M^{-1}(m)j = k!$  for **all**  $m \supseteq Im(\Phi_M)$ ?
  - 4*k* 2 [KMV12]

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## Theorem (**L.**, Améndola, Rodriguez)

Mixtures of k univariate Gaussians are rationally identifiable from moments  $m_1, \ldots, m_{3k+2}$ .

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## Theorem (**L.**, Améndola, Rodriguez)

Mixtures of k univariate Gaussians are rationally identifiable from moments  $m_1, \ldots, m_{3k+2}$ .

• Conjecture: Gaussian mixture models are rationally identifiable from  $m_1, \ldots, m_{3k}$ 

Solve moment equations

$$1 = m_0$$

$$\overline{m}_1 = m_1$$

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$$\overline{m}_{3k-1} = m_{3k-1}$$

over the complex numbers to get finitely many complex solutions

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- ② Filter out statistically meaningful solutions (real solutions with  $\lambda_i = 0, \sigma_i^2 > 0$ )
- **3** Select statistically meaningful solution agreeing with moments  $\overline{m}_{3k}$ ,  $\overline{m}_{3k+1}$ ,  $\overline{m}_{3k+2}$

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**Question:** How do I solve a square system of polynomial equations?

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• Let  $f_1, \ldots, f_m \supseteq \mathbb{R}[x_1, \ldots, x_n]$ . The (complex) variety of  $F = hf_1, \ldots, f_m/$  is

$$V(F) = fx \ 2 \ C^n : f_1(x) = 0, \dots, f_m(x) = 0g$$

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• Interested in case when n = m and JV(F)J < 1

Bezout Bound

• Consider JV(F)J < 1. **Question:** How big is JV(F)J?

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### Theorem (Bezout)

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# Theorem (BKK Bound [Ber75, Kho78, Kou76])

$$jV(F) \setminus (C)^n j \quad \text{MVol}(\text{Newt}(f_1), \dots, \text{Newt}(f_n))$$

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# Theorem (BKK Bound [Ber75, Kho78, Kou76])

$$jV(F) \setminus (C)^n j \quad \text{MVol}(\text{Newt}(f_1), \dots, \text{Newt}(f_n))$$

• In general, not easy to compute the mixed volume (#P hard)

Homotopy Continuation

• Idea: Solving most polynomial systems is hard, but some are easy

#### Homotopy Continuation

Idea: Solving most polynomial systems is hard, but some are easy

$$H_{T} = \begin{cases} 2(x_{2}x_{3} & x_{1}x_{4}) + 3x_{3} = 0\\ 2(x_{1}x_{4} & x_{2}x_{3}) + 4x_{4} = 0\\ x_{1}^{2} + x_{3}^{2} = 1\\ x_{2}^{2} + x_{4}^{2} = 1 \end{cases} \qquad H_{S} = \begin{cases} x_{1}^{2} = 1\\ x_{2}^{2} = 1\\ x_{3}^{2} = 1\\ x_{4}^{2} = 1 \end{cases}$$

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- Can I map my solutions from  $H_S$  to  $H_T$ ?
- Define  $H_t := \begin{pmatrix} 1 & t \end{pmatrix} H_S + t H_T$  and compute  $H_t$  as  $t \neq 1$ 
  - Called following homotopy paths

#### Homotopy Continuation

• Idea: Solving most polynomial systems is hard, but some are easy

$$H_{T} = \begin{cases} 2(x_{2}x_{3} & x_{1}x_{4}) + 3x_{3} = 0\\ 2(x_{1}x_{4} & x_{2}x_{3}) + 4x_{4} = 0\\ x_{1}^{2} + x_{3}^{2} = 1\\ x_{2}^{2} + x_{4}^{2} = 1 \end{cases} \qquad H_{S} = \begin{cases} x_{1}^{2} = 1\\ x_{2}^{2} = 1\\ x_{3}^{2} = 1\\ x_{4}^{2} = 1 \end{cases}$$

- Can I map my solutions from  $H_S$  to  $H_T$ ?
- Define  $H_t := (1 \quad t)H_S + tH_T$  and compute  $H_t$  as  $t \neq 1$ 
  - Called following homotopy paths
- Typically use predictor-corrector methods
  - Predict: Take step along tangent direction at a point
  - Correct: Use Newton's method

# Homotopy Continuation Visual

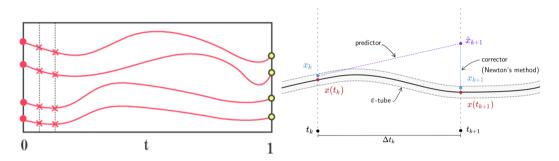


Figure: The homotopy  $H_t = (1 \quad t)H_S + tH_T$  (left)[KW14] and the predictor corrector step (right) [BT18]

- Want to pick a start system,  $H_S$ , such that
  - The solutions of  $H_S$  are easy to find
  - ② The number of solutions to  $H_S$  the number of solutions to  $H_T$

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- If  $jV(F)/d_1 = d_n$  then a **total degree** start system is suitable. i.e.

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- If  $jV(F)j = d_1 = d_n$  then a **total degree** start system is suitable. i.e.

$$H_{\mathcal{S}} = h x_1^{d_1} \quad 1, \dots, x_n^{d_n} \quad 1/2$$

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- If  $MVol(Newt(f_1), ..., Newt(f_n))$   $d_1$   $d_n$  then a **polyhedral** start system is suitable
- There exists an algorithm that finds this binomial start system [HS95]

# Examples of Start Systems

$$F = hx^2 \quad 3x + 2, \ 2xy + y \quad 1/2$$

Total degree:  $hx^2$  1,  $y^2$  1/

**Polyhedral:**  $hx^2 + 2$ , y = 1/

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- Problem Set Up
- 2 (Numerical) Algebraic Geometry Primer
- 3 Density Estimation for Gaussian Mixture Models
- 4 Applications in High Dimensional Statistics

#### Back to Gaussian Mixture Models

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- There are three special cases of Gaussian mixture models commonly studied in the statistics literature:
  - 1 The mixing coefficients are known
  - The mixing coefficients are known and the variances are equal
  - Only the means are unknown

#### Main Result

## Theorem (L., Améndola, Rodriguez [LAR21])

In all cases, Gaussian mixture models are algebraically identifiable using moment equations of lowest degree. Moreover, the mixed volume of each of set of equations is given below.

	Known mixing	Known mixing coefficients	Unknown
	coefficients	+ equal variances	means
Moment equations	$m_1,\ldots,m_{2k}$	$m_1,\ldots,m_{k+1}$	$m_1,\ldots,m_k$
Unknowns	$m_1,\ldots,m_{2k}$ $\mu_i,\sigma_i^2$	$\mu_i, \sigma^2$	$\mu_i$
Mixed volume	(2k 1)!!k!	$\frac{(k+1)!}{2}$	<i>k</i> !
Mixed volume tight	Yes for k 8	Yes for k 8	Yes

#### Classes of Gaussian Mixture Models

Solving the Polynomial Systems

	Mixed Volume	Bezout Bound
Known mixing coefficients	(2k 1)!!k!	(2k)!
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- Our proofs of the mixed volume in the first two cases give a start system that tracks mixed volume number of paths
- In the final case if  $\lambda_i = \frac{1}{k}$  and  $\sigma_i^2$  are equal, there is a unique solution up to symmetry

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### Gaussian Mixture Models

#### In high dimensions

• A random variable  $X \supseteq \mathbb{R}^n$  is distributed as a *multivariate Gaussian* with mean  $\mu \supseteq \mathbb{R}^n$  and covariance  $\Sigma \supseteq \mathbb{R}^n$ ,  $\Sigma$  0, if it has density

$$f_X(x_1,\ldots,x_n/\mu,\Sigma) = ((2\pi)^n \det(\Sigma))^{-1/2} \exp\left(-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)\right)$$

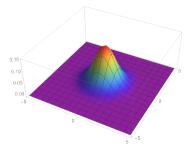


Figure: Gaussian density in 
$$\mathbb{R}^2$$
 with mean  $\mu=\begin{bmatrix}0\\0\end{bmatrix}$  and covariance  $\Sigma=\begin{bmatrix}1&0\\0&1\end{bmatrix}$ 

## Example

$$k = n = 2$$

Suppose  $X = \lambda_1 \mathcal{N}(\mu_1, \Sigma_1) + \lambda_2 \mathcal{N}(\mu_2, \Sigma_2)$  where

$$\mu_1 = \begin{pmatrix} \mu_{11} \\ \mu_{12} \end{pmatrix}, \qquad \qquad \Sigma_1 = \begin{pmatrix} \sigma_{111} & \sigma_{112} \\ \sigma_{112} & \sigma_{122} \end{pmatrix}$$

$$\mu_2 = \begin{pmatrix} \mu_{21} \\ \mu_{21} \end{pmatrix}, \qquad \qquad \Sigma_2 = \begin{pmatrix} \sigma_{211} & \sigma_{212} \\ \sigma_{212} & \sigma_{222} \end{pmatrix}.$$

The moment equations up to order 3 are

$$\begin{split} m_{00} &= \lambda_1 + \lambda_2 \\ m_{10} &= \lambda_1 \mu_{11} + \lambda_2 \mu_{21} \\ m_{01} &= \lambda_1 \mu_{12} + \lambda_2 \mu_{22} \\ m_{20} &= \lambda_1 (\mu_{11}^2 + \sigma_{111}) + \lambda_2 (\mu_{21}^2 + \sigma_{211}) \\ m_{11} &= \lambda_1 (\mu_{11} \mu_{12} + \sigma_{112}) + \lambda_2 (\mu_{21} \mu_{22} + \sigma_{212}) \\ m_{02} &= \lambda_1 (\mu_{12}^2 + \sigma_{122}) + \lambda_2 (\mu_{22}^2 + \sigma_{222}) \\ m_{30} &= \lambda_1 (\mu_{11}^3 + 3\mu_{11}\sigma_{111}) + \lambda_2 (\mu_{21}^3 + 3\mu_{21}\sigma_{211}) \\ m_{21} &= \lambda_1 (\mu_{11}^2 \mu_{12} + 2\mu_{11}\sigma_{112} + \mu_{12}\sigma_{111}) + \lambda_2 (\mu_{21}^2 \mu_{22} + 2\mu_{21}\sigma_{212} + \mu_{22}\sigma_{211}) \\ m_{12} &= \lambda_1 (\mu_{11} \mu_{12}^2 + \mu_{11}\sigma_{122} + 2\mu_{12}\sigma_{112}) + \lambda_2 (\mu_{21} \mu_{22}^2 + \mu_{21}\sigma_{222} + 2\mu_{22}\sigma_{212}) \\ m_{03} &= \lambda_1 (\mu_{12}^3 + 3\mu_{12}\sigma_{122}) + \lambda_2 (\mu_{22}^3 + 3\mu_{22}\sigma_{222}) \end{split}$$

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## Higher Order Moments

Application of Univariate Results

• **Key Observation:** The  $m_{0,0,\dots,0,i_t,0,\dots 0}$  th moment is the same as the  $i_t$  th order moment for the univariate Gaussian mixture model  $\sum_{\ell=1}^k \lambda_\ell \mathcal{N}(\mu_{\ell t}, \sigma_{\ell t t})$ 

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- Density estimation for high dimensional Gaussian mixture models becomes multiple instances of one dimensional problems
- Advantage: Only track the best statistically meaningful solution

 $\label{lem:condition} \mbox{Density Estimation for High Dimensional Gaussian Mixture Models}$ 

**Input**: A set of sample moments **m**<sup>1</sup>

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• Solve the general univariate case using sample moments  $\overline{m}_{0,...,0,1},\ldots,\overline{m}_{0,...,0,3k-1}$  to get parameters  $\lambda_{\ell}$ ,  $\mu_{\ell,1}$  and  $\sigma_{\ell,1,1}$ 

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- The covariances are linear in the other entries, solve this linear system

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# Example: (k, n) = (2, 2)

• Suppose  $X = \lambda_1 \mathcal{N}(\mu_1, \Sigma_1) + \lambda_2 \mathcal{N}(\mu_2, \Sigma_2)$  where

$$\mu_{1} = \begin{pmatrix} \mu_{11} \\ \mu_{12} \end{pmatrix}, \qquad \qquad \Sigma_{1} = \begin{pmatrix} \sigma_{111}^{2} & \sigma_{112} \\ \sigma_{112} & \sigma_{122}^{2} \end{pmatrix}$$

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• Given sample moments

$$[\overline{m}_{10}, \overline{m}_{20}, \overline{m}_{30}, \overline{m}_{40}, \overline{m}_{50}, \overline{m}_{60}] = [ 0.25, 2.75, 1.0, 22.75, 6.5, 322.75]$$

$$[\overline{m}_{01}, \overline{m}_{02}, \overline{m}_{03}, \overline{m}_{04}, \overline{m}_{05}] = [2.5, 16.125, 74.5, 490.5625, 2921.25]$$

$$[\overline{m}_{11}, \overline{m}_{21}] = [0.8125, 7.75]$$

#### Algorithm in Action

• **Step 1:** Solve general case to obtain  $\lambda_{\ell}, \mu_{\ell 1}, \sigma_{\ell 11}^2$  for  $\ell = 1, 2$ 

$$\begin{split} 1 &= \lambda_1 + \lambda_2 \\ 0.25 &= \lambda_1 \mu_{11} + \lambda_2 \mu_{21} \\ 2.75 &= \lambda_1 (\mu_{11}^2 + \sigma_{111}^2) + \lambda_2 (\mu_{21}^2 + \sigma_{211}^2) \\ 1 &= \lambda_1 (\mu_{11}^3 + 3\mu_{11}\sigma_{111}^2) + \lambda_2 (\mu_{21}^3 + 3\mu_{21}\sigma_{211}^2) \\ 22.75 &= \lambda_1 (\mu_{11}^4 + 6\mu_{11}^2\sigma_{111}^2 + 3\sigma_{111}^4) + \lambda_2 (\mu_{21}^4 + 6\mu_{21}^2\sigma_{211}^2 + 3\sigma_{211}^4) \\ 6.5 &= \lambda_1 (\mu_{11}^5 + 10\mu_{11}^3\sigma_{111}^2 + 15\mu_{11}\sigma_{111}^4) + \lambda_2 (\mu_{21}^5 + 10\mu_{21}^3\sigma_{211}^2 + 15\mu_{21}\sigma_{211}^4) \end{split}$$

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• (Up to symmetry) two statistically meaningful solutions:

$$(\lambda_1, \lambda_2, \mu_{11}, \mu_{21}, \sigma_{111}^2, \sigma_{211}^2) = (0.25, 0.75, 0, 1, 3, 1)$$
  
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Algorithm in Action

• **Step 3:** Using  $\lambda_1 = 0.25$ ,  $\lambda_2 = 0.75$  solve

$$\begin{aligned} 2.5 &= 0.25 \quad \mu_{12} + 0.75 \quad \mu_{22} \\ 16.125 &= 0.25 \quad (\mu_{12}^2 + \sigma_{122}^2) + 0.75 \quad (\mu_{22}^2 + \sigma_{222}^2) \\ 74.5 &= 0.25 \quad (\mu_{12}^3 + 3\mu_{12}\sigma_{122}^2) + 0.75 \quad (\mu_{22}^3 + 3\mu_{22}\sigma_{222}^2) \\ 490.5625 &= 0.25 \quad (\mu_{12}^4 + 6\mu_{12}^2\sigma_{122}^2 + 3\sigma_{122}^4) + 0.75 \quad (\mu_{22}^4 + 6\mu_{22}^2\sigma_{222}^2 + 3\sigma_{222}^4) \end{aligned}$$

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One statistically meaningful solution

$$(\mu_{12}, \mu_{22}, \sigma_{122}^2, \sigma_{222}^2) = (2, 4, 2, 3.5)$$

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One statistically meaningful solution

$$(\mu_{12}, \mu_{22}, \sigma_{122}^2, \sigma_{222}^2) = (2, 4, 2, 3.5)$$

• **Step 4:** Choose only statistically meaningful solution

Algorithm in Action

• **Step 5:** Solve the linear system

$$0.8125 = 0.25 \quad (2 + \sigma_{112}) + 0.75 \quad \sigma_{212}$$
  
 $7.75 = 0.25 \quad (4 + 2 \quad \sigma_{112}) + 9$ 

Algorithm in Action

• **Step 5:** Solve the linear system

$$0.8125 = 0.25 \quad (2 + \sigma_{112}) + 0.75 \quad \sigma_{212}$$
  
 $7.75 = 0.25 \quad (4 + 2 \quad \sigma_{112}) + 9$ 

There is one solution

$$(\sigma_{112}, \sigma_{212}) = (0.5, 0.25)$$

Algorithm in Action

• **Step 5:** Solve the linear system

$$0.8125 = 0.25 \quad (2 + \sigma_{112}) + 0.75 \quad \sigma_{212}$$
  
 $7.75 = 0.25 \quad (4 + 2 \quad \sigma_{112}) + 9$ 

There is one solution

$$(\sigma_{112}, \sigma_{212}) = (0.5, 0.25)$$

• Estimate that our samples came from density

$$0.25 \quad \mathcal{N}\left( \left[ \begin{array}{c} 1 \\ 2 \end{array} \right], \left[ \begin{matrix} 1 & 0.5 \\ 0.5 & 2 \\ \end{matrix} \right] \right) + 0.75 \quad \mathcal{N}\left( \left[ \begin{matrix} 0 \\ 4 \\ \end{matrix} \right], \left[ \begin{matrix} 3 & 0.25 \\ 0.25 & 3.5 \\ \end{matrix} \right] \right)$$

Computational Complexity

• Steps 3 and 4 can be run in parallel

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- Number of homotopy paths is linear in n
- Even simpler in cases where some of the parameters are known

Parameter Recovery



Figure: Two Gaussian mixture densities with k = 3 components and the same first eight moments.

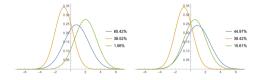


Figure: Individual components of two Gaussian mixture models with similar mixture densities.

## Computational Results

Density Estimation for High Dimensional Gaussian Mixture Models

• We perform the method of moments on the mixture of 2 Gaussians in  $\mathbb{R}^n$  with diagonal covariance matrices

n	10		100		1,000		10,000		100,000	
Time (s)	0.17		0.71		6.17		62.05		650.96	
Error	7.8	10 <sup>15</sup>	4.1	10 13	5.7	10 13	3.0	10 11	1.8	10 9
Normalized Error	1.9	10 <sup>16</sup>	1.0	10 <sup>15</sup>	1.4	10 16	7.3	10 16	4.5	10 15

Table: Average running time and numerical error for a mixture of 2 Gaussians in  $\mathbb{R}^n$ 

### Conclusion

- Gave new rational and algebraic identifiability results for Gaussian mixture models
- Gave upper bound for number of solutions to univariate Gaussian k mixture moment systems in three cases
- Applied these results to efficiently do density estimation in high dimensions

#### Thank you! Questions?

Paper: 'Estimating Gaussian mixture models using sparse polynomial moment systems'

arXiv:2106.15675

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